

## YellowScan Mapper.

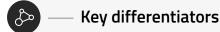
# The next-generation of integrated UAV LiDAR solution

YellowScan Mapper is next generation of integrated lidar solution.

It's low weight, mid-range capability, top-end point density and advanced accuracy and precision, makes it the best value for money in our portfolio.

It is dedicated to UAV borne mapping applications.





- High point density
- Compact
- Advanced point cloud precision



- Multirotor drones
- Helicopter drones
- Fixed-wings

## Technical specifications.

Scanner	Livox Horizon
Wavelength	905 nm
Precision <sup>(1) (3)</sup>	2 cm
Accuracy <sup>(2) (3)</sup>	3 cm
Scanner field of view	81.7 °
Shots per second	240k
Echoes per shot	Up to 2
GNSS-Inertial solution	Applanix APX-15 UAV

### General characteristics.

Weight	1.6 kg (3.5 lbs) battery included
Autonomy	1.5 hours typ.
Power consumption	19 W
Operating temperature	-20 to +40 °C
Size	L 14.4 x W 9.5 x H 14.2 cm

<sup>(1)</sup> Precision, also called reproducibility or repeatability, accounts for the variation in successive measurements taken on the same target.

## Package includes.

#### Hardware:

- YellowScan Mapper
- DJI Skyport adapter for M300 / M200
- Charger and 2 batteries
- GNSS antenna and cable
- 2 USB flash drives

#### Services:

- Boresight calibration certificate
- 1-year warranty
- In-person training
- Worldwide technical and operational support

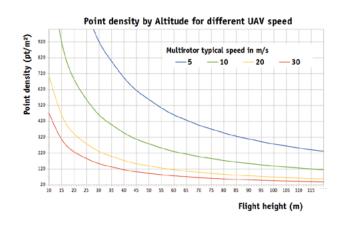
#### Software:

- Applanix POSPac UAV, to post-process GNSS and inertial data for highest accuracy
- YellowScan CloudStation, to generate and visualize your georeferenced point cloud

#### + Optional:

- Mounting bracket for DJI M600
- Single 20 Mpx camera module
- YellowScan LiveStation, the real-time in-flight LiDAR monitoring kit (software + 2 radio-modems)
- Warranty and technical support extensions

## Typical mission parameters.





**FLIGHT SPEED** 10 - 20 m/s



**ALTITUDE** 70 m



**SWATH** 120 m

<sup>(2)</sup> Accuracy is the degree of conformity of a measured position to its actual (true) value (3) One σ @ 50 m, nadir.